6.641 Electromagnetic Fields, Forces, and Motion Spring 2009

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6.641, Electromagnetic Fields, Forces, and Motion Prof. Markus Zahn Lecture 6: Magnetoquasistatics

I. MQS Governing Equations

$$\begin{split} \nabla \boldsymbol{\cdot} \left(\mu_0 \overline{H} \right) &= 0 \Rightarrow \mu_0 \overline{H} = \nabla \times \overline{A} & \left(\overline{A} = \text{vector potential} \right) \\ \nabla \times \overline{H} &= \frac{1}{\mu_0} \nabla \times \left(\nabla \times \overline{A} \right) = \overline{J} \\ \nabla \times \left(\nabla \times \overline{A} \right) &= \nabla \left(\nabla \boldsymbol{\cdot} \overline{A} \right) - \nabla^2 \overline{A} = \mu_0 \overline{J} \end{split}$$

II. Uniqueness

If $\overline{A} \to \overline{A} + \nabla \chi$, $\nabla \times \overline{A}$ is unchanged because $\nabla \times (\nabla \chi) = 0$

For $\nabla \cdot \overline{A}$ to also remained unchanged requires $\nabla^2 \chi = 0$

When, for EQS systems

 $\nabla^{2} \Phi = \frac{-\rho}{\epsilon} \Rightarrow \Phi\left(\bar{r}\right) = \int_{V'} \frac{\rho\left(\bar{r}'\right) dV'}{4\pi\epsilon \left|\bar{r}-\bar{r}'\right|}$

For $\nabla^2 \chi=0$ everywhere, it is analogous to $\rho=0$ everywhere for which $\Phi\left(\bar{r}\right)=0.$

Thus to uniquely specify a vector to within a constant, both its curl and divergence must be specified. Here, we have thus far specified $\nabla \times \overline{A} = \mu_0 \overline{H}$. We are free to specify $\nabla \cdot \overline{A}$ to any convenient value. We choose $\nabla \cdot \overline{A} = 0$ which is called setting the gauge. Then

 $\nabla^2 \overline{A} = -\mu_0 \overline{J}$

III. Vector Poisson's equation

$$\nabla^{2}\overline{A} = -\mu_{0}\overline{J} \Longrightarrow \nabla^{2}A_{x} = -\mu_{0}J_{x}$$
$$\nabla^{2}A_{y} = -\mu_{0}J_{y}$$
$$\nabla^{2}A_{z} = -\mu_{0}J_{z}$$





In analogy to the EQS Poisson's equation

$$\begin{aligned} \mathsf{A}_{x}\left(\bar{r}\right) &= \frac{\mu_{0}}{4\pi}\int_{V'}\frac{\mathsf{J}_{x}\left(\bar{r}^{\,\prime}\right)\mathsf{d}\mathsf{V}^{\prime}}{\left|\bar{r}-\bar{r}^{\,\prime}\right|} \\ \mathsf{A}_{y}\left(\bar{r}\right) &= \frac{\mu_{0}}{4\pi}\int_{V'}\frac{\mathsf{J}_{y}\left(\bar{r}^{\,\prime}\right)\mathsf{d}\mathsf{V}^{\prime}}{\left|\bar{r}-\bar{r}^{\,\prime}\right|} \\ \mathsf{A}_{z}\left(\bar{r}\right) &= \frac{\mu_{0}}{4\pi}\int_{V'}\frac{\mathsf{J}_{z}\left(\bar{r}^{\,\prime}\right)\mathsf{d}\mathsf{V}^{\prime}}{\left|\bar{r}-\bar{r}^{\,\prime}\right|} \end{aligned}$$

or in compact vector form

$$A(\mathbf{r}) = \frac{\mu_0}{4\pi} \int_{\mathbf{V}'} \frac{\overline{\mathbf{J}}(\mathbf{r},\mathbf{J})}{|\mathbf{r}-\mathbf{r}'|} d\mathbf{V}'$$

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IV. Boundary Conditions

1. Tangential \overline{H}

$$\nabla \times \overline{H} = \overline{J} \Rightarrow \oint_{C} \overline{H} \cdot \overline{ds} = \int_{S} \overline{J} \cdot \overline{da}$$



2. Single Current Sheet



3. Two Oppositely Directed Current Sheets



4. Normal H



 $\mu_{0} (H_{an} - H_{bn}) A = 0$ $H_{an} = H_{bn}$ $\overline{n} \cdot \left[\overline{H}_{a} - \overline{H}_{b}\right] = 0$

V. Biot - Savart Superposition Integral

$$\begin{split} \overline{H} &= \frac{1}{\mu_0} \nabla \times \overline{A} = \frac{1}{4\pi} \nabla \times \int_{V'} \frac{\overline{J}(\bar{r}') dV'}{\left| \bar{r} - \bar{r}' \right|} \\ &= \frac{1}{4\pi} \int_{V'} \nabla \times \left[\frac{\overline{J}(\bar{r}') dV'}{\left| \bar{r} - \bar{r}' \right|} \right] \end{split}$$

Let
$$\chi = \frac{1}{\left|\bar{r} - \bar{r}'\right|}$$

 $\nabla \times \left(\chi \,\bar{J}(\bar{r}')\right) = \chi \nabla \times \left(J(\bar{r}')\right) + \nabla \chi \times \bar{J}(\bar{r}')$

In a spherical coordinate system: $\nabla\left(\frac{1}{r}\right) = \overline{i}_r \frac{\partial}{\partial r}\left(\frac{1}{r}\right) = -\frac{1}{r^2} \overline{i}_r$

Therefore: $\nabla \left(\frac{1}{\left| \overline{r} - \overline{r}' \right|} \right) = \frac{-\overline{i}_{r'r}}{\left| \overline{r} - \overline{r}' \right|^2}$ $\overline{i}_{r'r} = \frac{\overline{r} - \overline{r}'}{\left| \overline{r} - \overline{r}' \right|}$



Figure 8.2.1 Spherical coordinate system with \mathbf{r}' located at origin.

Figure 8.2.2 Source coordinate \mathbf{r}' and observer coordinate \mathbf{r} showing unit vector $\mathbf{i}_{\mathbf{r}'\mathbf{r}}$ directed from \mathbf{r}' to \mathbf{r} .

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$$\nabla \times \left(\frac{\bar{\mathbf{J}}(\bar{\mathbf{r}}')}{\left| \bar{\mathbf{r}} - \bar{\mathbf{r}}' \right|} \right) = \frac{-\bar{\mathbf{i}}_{\mathbf{r}'\mathbf{r}}}{\left| \bar{\mathbf{r}} - \bar{\mathbf{r}}' \right|^2} \times \bar{\mathbf{J}}(\bar{\mathbf{r}}')$$
$$= \frac{\bar{\mathbf{J}}(\bar{\mathbf{r}}') \times \bar{\mathbf{i}}_{\mathbf{r}'\mathbf{r}}}{\left| \bar{\mathbf{r}} - \bar{\mathbf{r}}' \right|^2}$$

$$\overline{H} = \frac{1}{4\pi} \int_{V'} \frac{\overline{J}(\overline{r'}) \times \overline{i_{r'r}} dV'}{\left|\overline{r} - \overline{r'}\right|^2}$$

VI. On Axis Magnetic Field from Current Loop



$$\overline{J}(\overline{r}') \times \overline{i}_{r'r} dV' = iad\phi \overline{i}_{\phi} \times \left[\frac{z \overline{i}_{z} - a \overline{i}_{r}}{\sqrt{z^{2} + a^{2}}}\right] = \frac{iad\phi}{\sqrt{z^{2} + a^{2}}} \left[z \overline{i}_{r} + a \overline{i}_{z}\right]$$

$$\overline{H} = \frac{1}{4\pi} \int_{\phi=0}^{2\pi} \frac{ia \left[z \,\overline{i}_r + a \,\overline{i}_z \right] d\phi}{\sqrt{z^2 + a^2} \left[z^2 + a^2 \right]} = \frac{ia^2 \,\overline{i}_z}{2 \left[z^2 + a^2 \right]^{3/2}}$$

Hint: $\overline{i}_{r} = \cos \phi \, \overline{i}_{x} + \sin \phi \, \overline{i}_{y} \Rightarrow \int_{0}^{2\pi} \overline{i}_{r} \, d\phi = 0$



Figure 8.2.3 A solenoid consists of N turns uniformly wound over a length d, each turn carrying a current i. The field is calculated along the z axis, so the observer coordinate is at \mathbf{r} on the z axis.

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A. Superposition Approach Using Previous Result of Single Current Loop

Consider the solenoid as a collection of current loops, each of length dz'. For the loop at z' of thickness dz', the current in the loop is di = $\frac{\text{Ni}}{d}$ dz'. The magnetic field from this loop is

$$d\overline{H} = \frac{di a^{2}}{2\left[\left(z - z'\right)^{2} + a^{2}\right]^{3/2}} \overline{i}_{z} = \frac{Ni a^{2}dz'}{2d\left[\left(z - z'\right)^{2} + a^{2}\right]^{3/2}} \overline{i}_{z}$$

The total magnetic field is

$$H_{z} = \int_{z'=-\frac{d}{2}}^{+d/2} \frac{\text{Ni } a^{2}dz'}{2d\left[\left(z-z'\right)^{2}+a^{2}\right]^{\frac{3}{2}}} = \frac{\text{Ni } a^{2}}{2d} \int_{z'=-\frac{d}{2}}^{+d/2} \frac{dz'}{\left[\left(z-z'\right)^{2}+a^{2}\right]^{\frac{3}{2}}}$$

$$= \frac{\text{Nia}^2}{2d} \frac{(z'-z)}{a^2 \left[a^2 + (z-z')^2\right]^{\frac{1}{2}}} \bigg|_{z'=-\frac{d}{2}}^{\frac{d}{2}}$$
$$= \frac{\text{Ni}}{2d} \left[\frac{\frac{d}{2} - z}{\left[a^2 + \left(z - \frac{d}{2}\right)^2\right]^{\frac{1}{2}}} + \frac{\left(\frac{d}{2} + z\right)}{\left[a^2 + \left(z + \frac{d}{2}\right)^2\right]^{\frac{1}{2}}} \right]$$
$$\lim_{\frac{d}{2} \gg z} H_z = \frac{\text{Ni}}{2d} \frac{d}{\left[a^2 + \left(\frac{d}{2}\right)^2\right]^{\frac{1}{2}}}$$
$$\lim_{\frac{d}{2} \gg a} H_z = \frac{\text{Ni}}{d}$$

B. Solenoid modeled as Surface Current $\overline{K}=\frac{Ni}{d}\,\overline{i}_{\phi}$

$$\overline{H} = \frac{1}{4\pi} \int_{S'} \frac{\overline{K} \times \overline{i}_{r'r} dS}{\left|\overline{r} - \overline{r'}\right|^2}$$

$$\begin{split} &\overline{i}_{r'r} = -\overline{i}_{r} \sin \alpha - \overline{i}_{z} \cos \alpha \\ &\sin \alpha = \frac{a}{\sqrt{a^{2} + (z'-z)^{2}}}, \ \cos \alpha = \frac{(z'-z)}{\sqrt{a^{2} + (z'-z)^{2}}}, \ \left|\overline{r} - \overline{r}'\right|^{2} = \left[a^{2} + (z'-z)^{2}\right] \\ &\overline{H} = \frac{1}{4\pi} \int_{\phi=0}^{2\pi} \int_{z'=-\frac{d}{2}}^{+d/2} \frac{Ni}{d} \frac{\overline{i}_{\phi} \times \left[-\overline{i}_{r} \sin \alpha - \overline{i}_{z} \cos \alpha\right] a d\phi dz'}{\left[a^{2} + (z'-z)^{2}\right]} \\ &\text{Note:} \quad \int_{\phi=0}^{2\pi} \overline{i}_{r} d\phi = 0 \end{split}$$



VIII. Demonstration 8.2.1 Fields of a Circular Cylindrical Solenoid



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