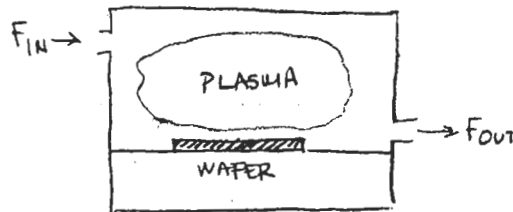


## SENSORS AND SIGNALS IN SEMICONDUCTOR MANUFACTURING

Available data for monitoring, control, and diagnosis can be categorized in several ways

### • STATE SENSED



- ① Wafer State  
e.g. film thickness, resistivity
  - ② Process/Environment State  
e.g. gas concentrations,  
ion density in plasma
  - ③ Equipment State  
e.g. machine settings, flows  
tool wear
- Often only indirect measures of state parameters are available
  - MODELS invariably needed to convert sensor signal to state information

### • DATA AVAILABILITY & TIMELINESS

- ① Real time - information available during process step
- vs. Run to Run - information available from one run (wafer, lot, batch) to the next
- vs. Many Timescales!
- ② In-situ - available with wafer in process (i.e. during processing)
- On-line - usually means the measurement can be automatically taken without additional operator intervention (e.g. on the process tool)
- In-line - usually a prescribed measurement as part of process flow
- Ex-situ - requires additional/separate measurement
- End-of-Line - available at end of process rather than right after a particular process ~~step~~

### • DATA STREAMS

- Multivariate & coupled
- Time-Series
- Spatial

## MULTIPLE CONTROL CHARTS - INDEPENDENT VARIABLES

- If we are simultaneously monitoring multiple quality characteristics, the univariate assumptions on type I (false alarm) rate are inaccurate...

Consider  $p$  statistically independent characteristics, where each chart has been set with  $\Pr\{\text{false alarm}\} = \alpha$ ;

⇒ What is overall probability of a false alarm? ( $\alpha'$ )

$$\alpha' = 1 - (1 - \alpha)^p \approx p \cdot \alpha \text{ for } \alpha \text{ small}$$

E.g. for 3 $\sigma$  control limits,  $\alpha = 0.0027$

With 2 charts  $\alpha' = 0.0054$

5 charts  $\alpha' = 0.0134$

10 charts  $\alpha' = 0.0267$

100 charts  $\alpha' = 0.2369$

Many more false alarms!!

Or to look at it another way, the

$$\Pr\{\text{all plot inside limit / in control}\} = (1 - \alpha)^p \approx 1 - p\alpha$$

- This is a common problem: a complicated tool may have 30 charts! with ARL = 370 for false alarm on univariate chart design ⇒ false alarm every 12 runs!
- Approach: ① USE CORRECT  $\alpha$  based on OVERALL  $\alpha'$  RISK!

$$\alpha = 1 - (1 - \alpha')^{1/p} \quad (\text{approximately } \alpha = \alpha'/p)$$

Example: 10 control charts

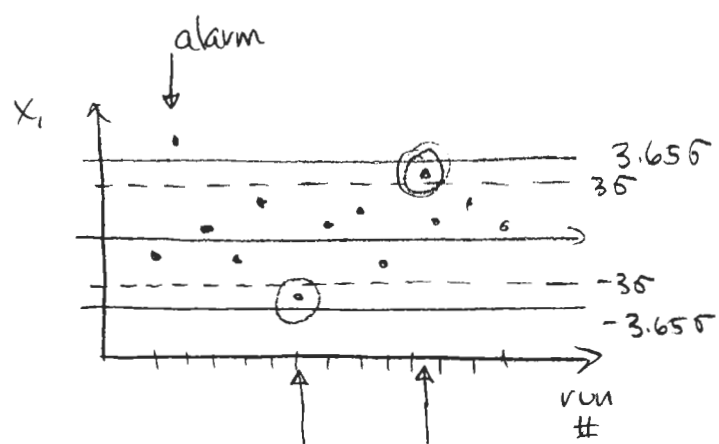
$$\alpha' = 0.0027 \quad \text{gives} \quad z_{\alpha'/2} = 3 \quad (3\sigma \text{ rule})$$

multivariate limits

$$\Rightarrow \alpha = 0.00027$$

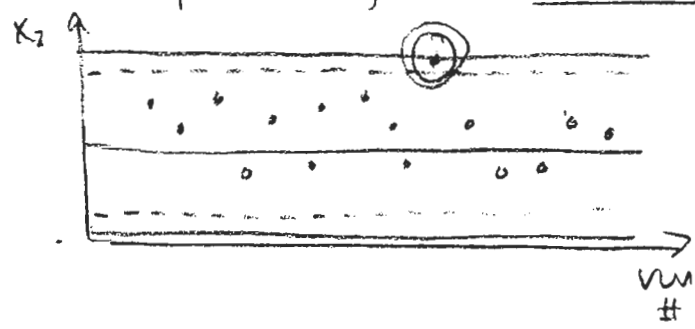
$$z_{\alpha/2} = \underline{\underline{3.65}}$$

Appropriately Expanded Control Limit

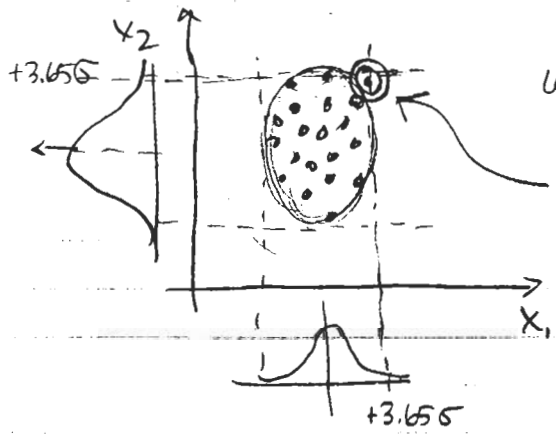


Would have been univariate alarms, but we ignore. Why?  
 ⇒ build in extra "deadzone" for false alarms

② We could also include additional rules based on probability of simultaneous excursions...



• Indeed, we can formalize this "joint distance" notion. Suppose, as we have assumed, that  $X_1$  &  $X_2$  are bivariate independent normal distributions:



where  $\sigma_2 > \sigma_1$   
 e.g. Point inside individual charts — but if "high" in multiple charts this is very unlikely & thus should be an alarm.

What we're looking for is some "generalized distance" measure that

- and
- (1) captures total deviation from mean (centroid)
  - (2) weights distance in each direction by likelihood of points in that direction ( $\sigma_{xi}$ )

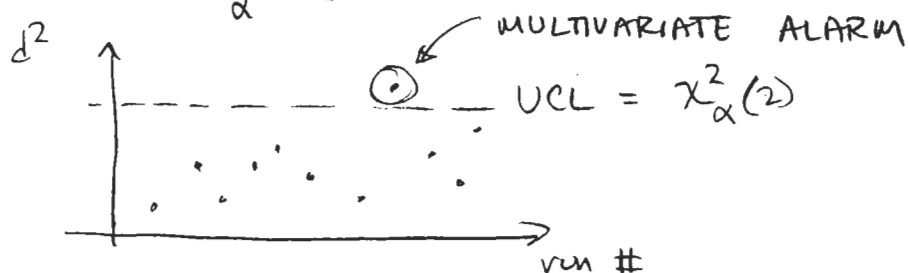
$$d = \sqrt{\left(\frac{x_1 - \mu_1}{\sigma_1}\right)^2 + \left(\frac{x_2 - \mu_2}{\sigma_2}\right)^2}$$

$$d^2 = \left(\frac{x_1 - \mu_1}{\sigma_1}\right)^2 + \left(\frac{x_2 - \mu_2}{\sigma_2}\right)^2 = \frac{\sigma_2^2 (x_1 - \mu_1)^2 + \sigma_1^2 (x_2 - \mu_2)^2}{\sigma_1^2 \sigma_2^2}$$

Where  $d^2 \sim \chi^2(2)$  Chi-Square with 2 degrees of freedom  
(by definition of Chi-Square!)

### • Chi-Square Control Chart

We can plot for each run the  $d^2$  statistic, and set control limits based on OVERALL  $\alpha$ -risk in the  $\chi^2_\alpha$  distribution:



For UNCORRELATED set of data, we can also extend to  $p$  dimensions: the distance measure for any single point at  $(x_1, x_2, \dots, x_p)$  is

$$d^2 = \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \\ \vdots \\ x_p - \mu_p \end{bmatrix}^T \begin{bmatrix} \sigma_1^2 & 0 & \dots & 0 \\ 0 & \sigma_2^2 & & \\ \vdots & & \ddots & \\ 0 & 0 & & \sigma_p^2 \end{bmatrix}^{-1} \begin{bmatrix} x_1 - \mu_1 \\ x_2 - \mu_2 \\ \vdots \\ x_p - \mu_p \end{bmatrix}$$

$$= [x_1 - \mu_1 \quad \dots \quad x_p - \mu_p] \begin{bmatrix} \frac{1}{\sigma_1^2} & & 0 \\ & \frac{1}{\sigma_2^2} & \\ 0 & & \frac{1}{\sigma_p^2} \end{bmatrix} \begin{bmatrix} x_1 - \mu_1 \\ \vdots \\ x_p - \mu_p \end{bmatrix}$$

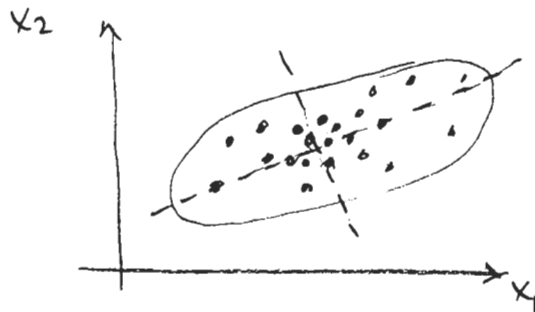
$$= \begin{bmatrix} \frac{x_1 - \mu_1}{\sigma_1^2} & & 0 \\ & \frac{x_2 - \mu_2}{\sigma_2^2} & \\ 0 & & \frac{x_p - \mu_p}{\sigma_p^2} \end{bmatrix} \begin{bmatrix} x_1 - \mu_1 \\ \vdots \\ x_p - \mu_p \end{bmatrix}$$

$$= \frac{(x_1 - \mu_1)^2}{\sigma_1^2} + \dots + \frac{(x_p - \mu_p)^2}{\sigma_p^2}$$

## CHI-SQUARE CONTROL CHARTS - CORRELATED VARIABLES

- If we are monitoring quality characteristics on the same product, or on the same process, it is quite likely that these characteristics are indeed **CORRELATED**.

How handle such cases?



Statistically dependent  
 $\Rightarrow$  knowing value of  $x_1$ ,  
 changes the probability  
 of some  $x_2$  value

(e.g. a "high"  $x_1$  means I'm  
 also more likely to have a  
 "high"  $x_2$ ).

- $\therefore$  Our independent case "distance" metric will overstate the true probability distance; we should discount for correlation:

$$d^2 = \frac{1}{\sigma_1^2 \sigma_2^2 - \rho_{12}^2} \left[ \sigma_2^2 (x_1 - \mu_1)^2 + \sigma_1^2 (x_2 - \mu_2)^2 - 2\rho_{12}(x_1 - \mu_1)(x_2 - \mu_2) \right]$$

Or, in matrix notation for  $p$  output variables:

$$d^2 = (\vec{x} - \vec{\mu})^T \vec{\Sigma}^{-1} (\vec{x} - \vec{\mu})$$

where  $\vec{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \\ \vdots \\ \mu_p \end{bmatrix}$  mean vector

$\vec{\Sigma} =$  covariance matrix =

$$\begin{bmatrix} \sigma_1^2 & \rho_{12} & \rho_{13} & \dots \\ \rho_{12} & \sigma_2^2 & & \\ \rho_{13} & \rho_{23} & \sigma_3^2 & \\ \vdots & & & \ddots \\ & & & & \sigma_p^2 \end{bmatrix}$$

$d^2 \sim \chi^2(p)$  Chi-square  
 with  $p$  d.o.f.

## Variance & Covariance - Linear Algebraic Picture

① Sample variance

$$\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_r \end{bmatrix} \quad r \text{ samples}$$

$$\vec{m} = \vec{x} - \bar{x} = \begin{bmatrix} x_1 - \bar{x} \\ \vdots \\ x_r - \bar{x} \end{bmatrix} \quad \text{mean centered}$$

$$s^2 = \frac{\vec{m}^T \vec{m}}{r-1} = \frac{\begin{bmatrix} x_1 - \bar{x} \\ \vdots \\ x_r - \bar{x} \end{bmatrix}^T \begin{bmatrix} x_1 - \bar{x} \\ \vdots \\ x_r - \bar{x} \end{bmatrix}}{r-1} = \frac{\|\vec{m}\|^2}{r-1} \quad \text{"length" of vector}$$

$$= \begin{bmatrix} x_1 - \bar{x} & \dots & x_r - \bar{x} \end{bmatrix} \begin{bmatrix} x_1 - \bar{x} \\ \vdots \\ x_r - \bar{x} \end{bmatrix} \frac{1}{r-1}$$

$$\hat{\sigma}_x^2 = \hat{\sigma}_{xx}^2 = s^2 = \frac{1}{r-1} \sum_{i=1}^r (x_i - \bar{x})^2 \quad \text{as before}$$

② Covariance between two variables ...

$$\hat{\sigma}_{xy}^2 = s_{xy}^2 = \frac{1}{r-1} (\vec{x} - \bar{x})^T (\vec{y} - \bar{y})$$

$$= \frac{1}{r-1} \begin{bmatrix} x_1 - \bar{x} & \dots & x_r - \bar{x} \end{bmatrix} \begin{bmatrix} y_1 - \bar{y} \\ \vdots \\ y_r - \bar{y} \end{bmatrix}$$

$$\hat{\sigma}_{x_1 \cdot x_2}^2 = s_{12}^2 = \frac{1}{r-1} \begin{bmatrix} \vec{x}_1 - \bar{x}_1 \end{bmatrix}^T \begin{bmatrix} \vec{x}_2 - \bar{x}_2 \end{bmatrix} \quad \text{where } \vec{x}_2 = \begin{bmatrix} x_{21} \\ x_{22} \\ \vdots \\ x_{2r} \end{bmatrix} \begin{matrix} r \text{ rows} \\ 2^{\text{nd}} \text{ variable} \end{matrix}$$

③ Extend to  $n$  variables

$$\begin{bmatrix} \vec{x}_1 - \bar{x}_1 & \vec{x}_2 - \bar{x}_2 & \dots & \vec{x}_n - \bar{x}_n \end{bmatrix} = \vec{M} = \begin{bmatrix} \vec{x} - \bar{x} \end{bmatrix}$$

So

$$C = \text{Sample Covariance} = \frac{1}{r} M^T M$$



## T<sup>2</sup> CONTROL CHART - Estimated means & covariance

- In direct analog to the univariate case, we often do not know the process mean and covariance, and must estimate them:

$$\vec{\bar{x}} = \hat{\vec{\mu}} \quad \text{That is, } \begin{bmatrix} \bar{x}_1 \\ \bar{x}_2 \\ \vdots \\ \bar{x}_p \end{bmatrix} = \begin{bmatrix} \hat{\mu}_1 \\ \vdots \\ \hat{\mu}_p \end{bmatrix}$$

$$\vec{S} = \hat{\Sigma} \quad \text{That is, the sample covariance estimates the process covariance.}$$

Then a statistic, the **HOTELLING T<sup>2</sup>**, is

$$T^2 = (\vec{x} - \vec{\bar{x}})^T \vec{S}^{-1} (\vec{x} - \vec{\bar{x}}) \sim F_{p, m-p}$$

gives us the same "weighted" generalized distance measure, but now using the estimated covariance.

- In general, we may use samples with  $n$  individuals, and base our estimates  $\vec{S}$  on  $m$  previous or preliminary runs:

$$T^2 = n (\bar{x} - \bar{\bar{x}})^T \vec{S}^{-1} (\bar{x} - \bar{\bar{x}}) \quad \text{(dropped vector, use } \bar{\bar{x}} = \hat{\vec{\mu}})$$

and set 
$$UCL = \frac{p(m+1)(n-1)}{mn-m-p+1} F_{\alpha, p, mn-m-p+1}$$

- Example: two variable uncorrelated case

$$T^2 = \frac{(\bar{x}_1 - \bar{\bar{x}})^2}{S_1^2} + \frac{(\bar{x}_2 - \bar{\bar{x}})^2}{S_2^2} \sim F_{2, m-2}$$

- When  $m$  is large ( $m > 20-50$ ), usually take  $\vec{S}$  estimate to be very good, and simply use

$$UCL = \chi^2_{\alpha, p}$$

## Estimating Covariance

Samples of size  $n$ ,  $i = 1, 2, \dots, n$   
 Output variables  $p$ ,  $j = 1, 2, \dots, p$   
 Preliminary runs  $m$ ,  $k = 1, 2, \dots, m$

$$\bar{x}_{jk} = \frac{1}{n} \sum_{i=1}^n x_{ijk} \quad \dots \text{mean for each sample}$$

$$S_{jk}^2 = \frac{1}{n-1} \sum_{i=1}^n (x_{ijk} - \bar{x}_{jk})^2 \quad \dots \text{variance for each sample}$$

} as usual.

Covariance between characteristic  $j$  and  $h$  in  $k^{\text{th}}$  run:

$$S_{jh,k} = \frac{1}{n-1} \sum_{i=1}^n (x_{ijk} - \bar{x}_{jk})(x_{ihk} - \bar{x}_{hk}) \quad \begin{matrix} j, h = 1, 2, \dots, p \\ j \neq h \end{matrix}$$

Now we average over the  $m$  runs:

$$\bar{x}_j = \frac{1}{m} \sum_{k=1}^m \bar{x}_{jk} \quad j = 1, 2, \dots, p$$

$$\bar{S}_j^2 = \frac{1}{m} \sum_{k=1}^m S_{jk}^2 \quad j = 1, 2, \dots, p \quad \text{--- variance parts}$$

and

$$\bar{S}_{jh} = \frac{1}{m} \sum_{k=1}^m S_{jhk} \quad j \neq h$$

So

$$\bar{S} = \begin{bmatrix} \bar{S}_1 & \bar{S}_{12} & \bar{S}_{13} & \dots & \bar{S}_{1p} \\ \vdots & \bar{S}_2 & & & \\ & & \ddots & & \\ \bar{S}_{p1} & & & & \bar{S}_p \end{bmatrix}$$

• EXAMPLE: tensile strength & diameter

$n = 10$  sample size

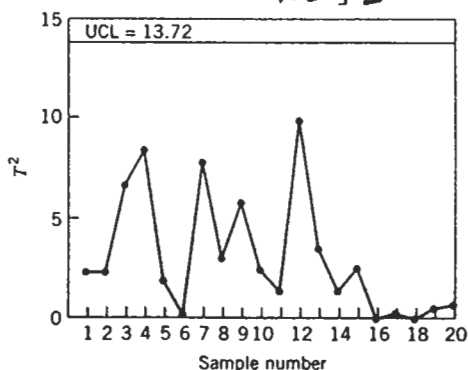
$m = 20$  preliminary samples

Sample Number $k$	(a) Sample Means		(b) Variances and Covariances			(c) Control Chart Statistics	
	Tensile Strength ( $\bar{x}_{1k}$ )	Diameter ( $\bar{x}_{2k}$ )	$S_{1k}^2$	$S_{2k}^2$	$S_{12k}$	$T_k^2$	$ S_k $
1	115.25	1.04	1.25	0.87	0.80	2.16	0.45
2	115.91	1.06	1.26	0.85	0.81	2.14	0.41
3	115.05	1.09	1.30	0.90	0.82	6.77	0.50
4	116.21	1.05	1.02	0.85	0.81	8.29	0.21
5	115.90	1.07	1.16	0.73	0.80	1.89	0.21
6	115.55	1.06	1.01	0.80	0.76	0.03	0.23
7	114.98	1.05	1.25	0.78	0.75	7.54	0.41
8	115.25	1.10	1.40	0.83	0.80	3.01	0.52
9	116.15	1.09	1.19	0.87	0.83	5.92	0.35
10	115.92	1.05	1.17	0.86	0.95	2.41	0.10
11	115.75	0.99	1.45	0.79	0.78	1.13	0.54
12	114.90	1.06	1.24	0.82	0.81	9.96	0.36
13	116.01	1.05	1.26	0.55	0.72	3.86	0.17
14	115.83	1.07	1.17	0.76	0.75	1.11	0.33
15	115.29	1.11	1.23	0.89	0.82	2.56	0.42
16	115.63	1.04	1.24	0.91	0.83	0.70	0.19
17	115.47	1.03	1.20	0.95	0.70	0.19	0.65
18	115.58	1.05	1.18	0.83	0.79	0.00	0.36
19	115.72	1.06	1.31	0.89	0.76	0.35	0.59
20	115.40	1.04	1.29	0.85	0.68	0.62	0.63
Averages	$\bar{\bar{x}}_1 = 115.59$	$\bar{\bar{x}}_2 = 1.06$	$\bar{S}_1^2 = 1.23$	$\bar{S}_2^2 = 0.83$	$\bar{S}_{12} = 0.79$		

For control, will calculate

$$T^2 = \frac{10}{(1.23)(0.83) - (0.79)^2} \left[ 0.83 (\bar{\bar{x}}_1 - 115.59)^2 + 1.23 (\bar{\bar{x}}_2 - 1.06)^2 - 2(0.79)(\bar{\bar{x}}_1 - 115.59)(\bar{\bar{x}}_2 - 1.06) \right]$$

Use  $UCL \approx \chi^2_{0.001, 2} = 13.816$



No evidence of poor control during preliminary runs  $\Rightarrow$  accept chart

## • INTERPRETING ALARMS

- A disadvantage of multivariate charts is determining what is responsible for signal.

Approaches: (1) Standard practice: plot univariate  $\bar{x}_i$ ;  
 → may not succeed!

(2) Decompose  $T^2$  into components reflecting contribution of  $i$ th variable;

$$d_i = T^2 - T^2(i)$$

where

$T^2(i)$  = statistic for all process variable except  $i$ th

⇒ look for  $d_i$  large...

## PRINCIPAL COMPONENT ANALYSIS

- Raw Data  $L$ ,  $r \times n$ ,  $r = \#$  experimental runs  
 $n = \#$  measurements or variables  
 per run

$$L_{ij} = \text{ith run, } j^{\text{th}} \text{ data variable.}$$

- Mean Centering: Average across  $\#$  runs (that is, average column)

$$M_{ij} = L_{ij} - \bar{L}_j$$

so  $\bar{L}_j$  is sample mean of the  $j^{\text{th}}$  column across  $r$  runs

- Sample Covariance

$$C = \frac{1}{r-1} M^T M$$

$C$  is  $n \times n$  capturing relationships between variables

- Eigenvector - Right Eigenvectors

$$C V = V \Lambda$$

where

$V$  is  $n \times n$  eigenvector matrix  
 $\Lambda$  is  $n \times n$  diagonal

- Can efficiently compute using SVD

$$-\Lambda = \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & & \\ 0 & 0 & \dots & \\ & & & \lambda_2 \end{bmatrix}$$

- Projection onto some principal direction (eigenvector):

$$M v_j = t_j$$

where  $t_j$  are the "score" or loadings on the principal directions

or, as a whole

$$M V = T$$

Note that  $-\Lambda = \frac{1}{r-1} T^T T$ ; that is to say, the  $T$  vectors are orthogonal and capture all the covariance in the original data.

$$\text{Since } V^T V = I$$

• Dimensionality Reduction

A key use of PCA is to select only those components that matter - a reduced # of effective dimensions in the data.

- Variation captured in each P.C. (eigenvector):

order  $\Lambda = [\lambda_1 \lambda_2 \dots \lambda_n]$  in decreasing order

$$\lambda_1 \gg \lambda_2 \gg \lambda_3 \gg \dots \lambda_n$$

$$\% \text{ variance in eigenvector } v_j = \frac{\lambda_j \cdot 100}{\sum_j \lambda_j} = \frac{\lambda_j \cdot 100}{\text{Trace}(C)}$$

So, if want say 97% or 99% of variation to be captured in the model, pick top  $\lambda_j, v_j$  that capture as desired:

e.g.  $\hat{T} = [t_1 \ t_2 \ t_3 \ t_4]$

$$M \hat{V} = \hat{T}$$

↑ just project onto desired "top" directions