



Introduction to Numerical Analysis for Engineers

Mathews

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Initial Value Problems

Higher Order Differential Equations

Differential Equation

$$y^{(n)}(t) = f(t, y, y', \dots, y^{(n-1)})$$

$$y(t_0) = y_0$$

$$y'(t_0) = y_1$$

.

.

$$y^{(n-1)}(t_0) = y_{n-1}$$

Initial
Conditions

Convert to 1st Order System

$$\left. \begin{array}{l} x_1 = y \\ x_2 = y' \\ x_3 = y'' \\ \cdot \\ \cdot \\ x_n = y^{(n-1)} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} x'_1 = x_2 \\ x'_2 = x_3 \\ x'_3 = x_4 \\ \cdot \\ \cdot \\ x'_n = f(t, x_1, x_2, \dots, x_n) \end{array} \right. \quad \begin{array}{l} x_1(t_0) = y_0 \\ x_2(t_0) = y_1 \\ x_3(t_0) = y_2 \\ \cdot \\ \cdot \\ x_n(t_0) = y_{n-1} \end{array}$$

Matrix form

$$\bar{\mathbf{x}}' = \bar{\mathbf{A}}\bar{\mathbf{x}} + \bar{\mathbf{g}}$$

$$\bar{\mathbf{x}} = \begin{Bmatrix} x_1 \\ x_2 \\ \cdot \\ \cdot \\ x_n \end{Bmatrix}, \quad \bar{\mathbf{A}} = \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \cdot & & \cdot \\ \cdot & & \cdot \\ a_{n1} & \cdots & a_{nn} \end{bmatrix}$$

Solved using e.g. Runge-Kutta (ode45)



Boundary Value Problems

Shooting Method

Differential Equation

$$y'' = f(x, y, y')$$

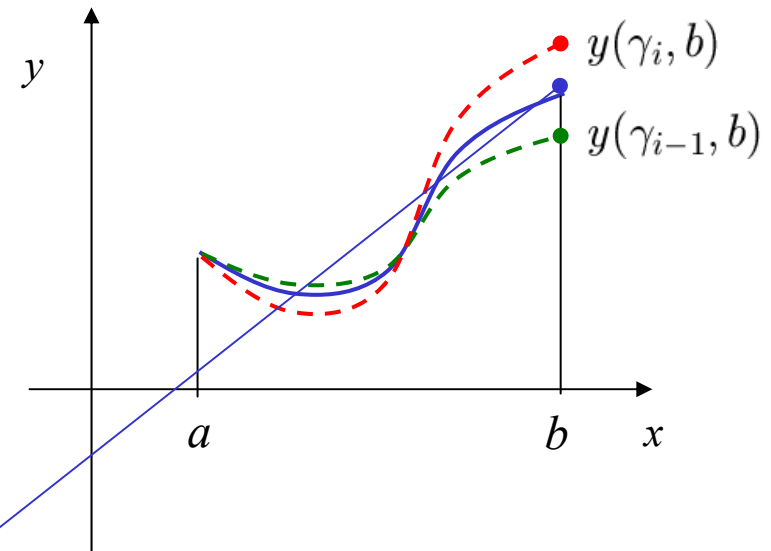
$$\left. \begin{aligned} y(a) &= y_a \\ y(b) &= y_b \end{aligned} \right\} \text{Boundary Conditions}$$

'Shooting' Method

$$\left. \begin{aligned} y'' &= f(x, y, y') \\ y(a) &= y_a \\ y'(a) &= \gamma_i \end{aligned} \right\} \begin{aligned} &\rightarrow y(\gamma_i, b) \\ &\text{Initial value Problem} \\ &\text{Solve by Runge-Kutta} \end{aligned}$$

'Shooting' Iteration

$$\gamma_{i+1} = \gamma_{i-1} + (\gamma_i - \gamma_{i-1}) \frac{y_b - y(\gamma_{i-1}, b)}{y(\gamma_i, b) - y(\gamma_{i-1}, b)}$$





Boundary Value Problems

Direct Finite Difference Methods

Differential Equation

$$y'' = f(x, y, y')$$

$$\left. \begin{aligned} y(a) &= y_a \\ y(b) &= y_b \end{aligned} \right\} \text{Boundary Conditions}$$

Discretization

$$h = \frac{b - a}{N}$$

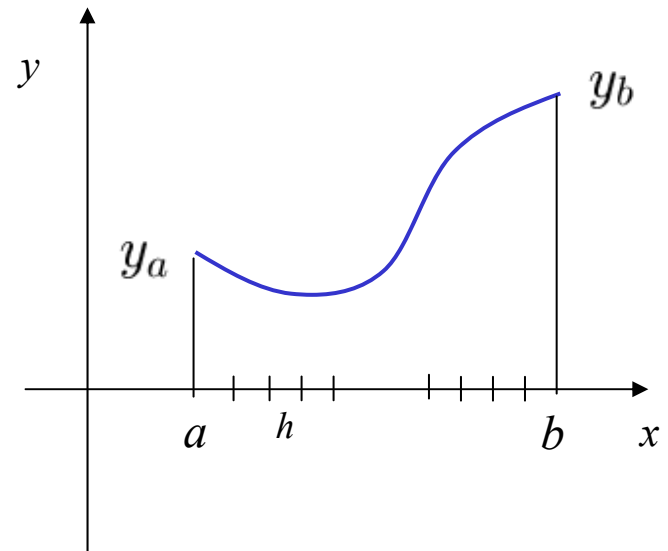
$$x_n = a + nh, \quad n = 0, 1, \dots, N$$

Finite Differences

$$y_n = y(x_n)$$

$$y'_n = y'(x_n) = \frac{y_{n+1} - y_{n-1}}{2h} + O(h^2)$$

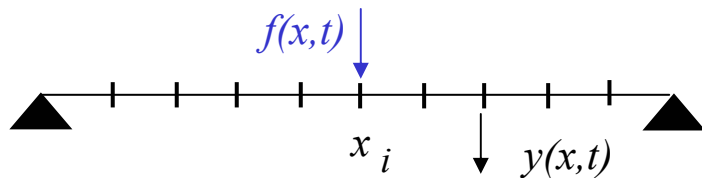
$$y''_n = y''(x_n) = \frac{y_{n+1} - 2y_n + y_{n-1}}{h^2} + O(h^2)$$





Boundary Value Problems Finite Difference Methods

Forced Vibration of a String



Harmonic excitation

$$f(x,t) = f(x) \cos(\omega t)$$

Differential Equation

$$\frac{d^2 y}{dx^2} + k^2 y = f(x)$$

Boundary Conditions

$$y(0) = 0, \quad y(L) = 0$$

Finite Difference

$$\left. \frac{d^2 y}{dx^2} \right|_{x_i} \simeq \frac{y_{i-1} - 2y_i + y_{i+1}}{h^2}$$

Discrete Difference Equations

$$y_{i-1} + ((kh)^2 - 2)y_i - y_{i+1} = f(x_i)h^2$$

Matrix Form

$$\begin{bmatrix} (kh)^2 - 2 & 1 & \cdot & \cdot & \cdot & \cdot & 0 \\ 1 & (kh)^2 - 2 & 1 & & & & \cdot \\ \cdot & & \cdot & \cdot & & & \cdot \\ \cdot & & & 1 & (kh)^2 - 2 & 1 & \cdot \\ \cdot & & & & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & \cdot & \cdot & \cdot & 1 & (kh)^2 - 2 \end{bmatrix} \bar{x} = \begin{Bmatrix} f(x_1)h^2 \\ \cdot \\ \cdot \\ f(x_i)h^2 \\ \cdot \\ \cdot \\ f(x_n)h^2 \end{Bmatrix}$$

Tridiagonal Matrix

$kh < 1$ Symmetric, positive definite: No pivoting needed



Boundary Value Problems Finite Difference Methods

Boundary Conditions with Derivatives

$$y'' - yx = g(x)$$

$$y(a) = 0$$

Central Difference $y'(b) = 0$

Difference Equations

$$y_0 = 0$$

$$y_{n-1} - 2y_n + y_{n+1} - h^2 y_n x_n = h^2 g(x_n), \quad n = 1,$$

$$y_N = ?$$

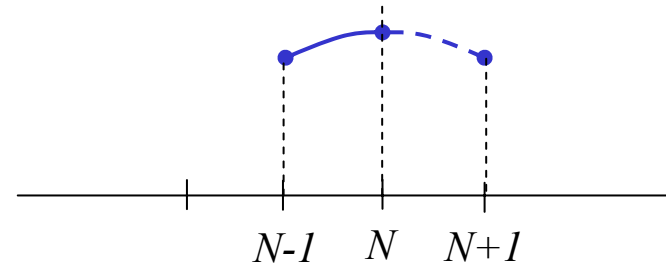
Backward Difference

$$y'(b) = 0 = \frac{y_N - y_{N-1}}{h} + O(h)$$

$$y_0 = 0 \quad O(h^4)$$

$$y_{n-1} - 2y_n + y_{n+1} - h^2 y_n x_n = h^2 g(x_n), \quad n = 1, 2, \dots, N-1$$

$$y_N - y_{N-1} = 0 \quad O(h^2)$$



Central Difference

$$y'(b) = 0 = \frac{y_{N+1} - y_{N-1}}{2h} + O(h^2)$$

$$y_0 = 0$$

$$y_{n-1} - 2y_n + y_{n+1} - h^2 y_n x_n = h^2 g(x_n), \quad n = 1, 2, \dots, N-1$$

$$2(y_{N-1} - y_N) - h^2 y_N x_N = 0 \quad O(h^3)$$

General Boundary Conditions

$$p_0 y(b) + p_1 y'(b) = p_2$$

Finite Difference Representation

$$p_0 y_N + \frac{p_1 (y_{N+1} - y_{N-1})}{2h} = p_2$$

Add extra point - N equations, N unknowns